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REPOTRIC TIME-REPORT DEVICE

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ment devices such as are used for example necessary operative engagement between the for closing or opening circuits when some

predetermined time interval has elapsed after the action of the device has been started

Various types of such devices are known, driven in various ways for instance by spring or weight driven clockwork trains or 10 by electric motors

In certain situations, as for example in a central station or substation it is often necessary to employ two or more of such timeelement devices and according to this in-

- 15 vention, instead of using a number of separate elements each with its own driving member, what may be termed a multiple time-element device is employed having one driving member with which, when required,
- 20 any or all of the separate devices can be brought into or out of operative engagement

This common driving member may be of any suitable form but it is preferred to make

25 it as a shaft rotated at a slow and uniform speed by a small electric motor driving the shaft through a worm reduction gear

Upon this shaft are mounted a number of toothed punions or other driving members so which rotate with the shaft, each one of these pinions being in proximity to a gear wheel on the spindle of one of the separate

time-element devices Thus for example the driving shaft may at have mounted upon it four pinions and there may be two time-element devices mounted on the same base or bed-plate on each side of the shaft, each time-element device having a spindle parallel to the driving shaft 40 and bearing a gear wheel which can be brought into engagement with the proper

pinion on the driving shaft. The operative engagement between each

driving pinion and its time-element device 45 may be brought about in any convenient way but preferably the driving pinion is fixed on the common diiving shaft and the spindle and gear wheel of the time-element device are moved the requisite short dis-50 tance to bring the teeth of the gear wheel into and out of mesh with those of the driv-

ing pinion, Conveniently each time-element comprises a solenoid or electromagnet which of the spindle due to the engagement of the when energized moves its spindle against time-element device with the common driv-

This invention relates to electric time-ele- the action of a spring so as to make the 55 gears This engagement will continue so long as the solenoid or electromagnet is energized and disengagement will then be effected by means of the spring

Each time-element is provided with a contact-making device or devices operated by the rotation of its spindle For instance the spindle may carry a disc having a peripheral cam surface or two or more inde- 65 pendent cam surfaces each such surface cooperating with one end of a pivoted lever or levers and the other, end of such levers may control the position of spring contacts so that at any desired point in the cam pe- 70 riphery such contacts may be either closed or opened as desired This enables any desired sequence of operations which is dependent on the circuits controlled by the spring contacts, to be either started or 75 stopped in the right order, and with any desired time interval between the respective operations Or again the cam or contactmaking disc may be driven from the spindle of the time-element device through a worm and worm wheel This latter construction is preferably used when a long time interval is required between the moment when the electromagnet or solenoid is energized and that at which the contact is required to be 85 made.

Or again, the cam or cams may be made to operate mechanically locking or tripping devices, either independently or in conjunction with electrical circuits, so that when 9. operated such trips or circuits cannot be re-operated until reset by independent device, or by hand after inspection By such means, should any sequence of operations persist beyond a desired point, these opera- 96 tions can be stopped, and any risk of failure or accident prevented

Each time-element device is so constructed that it is automatically returned to its zero position when it is brought out of 100 operative engagement with the common diving member This resetting operation may be either instantaneous, approximate average or average resetting Such resetting may be conveniently brought about by 105 a spring which is wound up by the rotation

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ing member, such spring starting to rotate time-element contact making devices C and the spindle in the opposite direction and reset the time-element as soon as disengagement is effected

- For instance when quick or practically 5 instantaneous resetting is required the spring may act directly on the spindle of the time-element device On the other hand should average time resetting be de-
- 10 sired and the time-element spindle drive the contact-making cam through gear, then the spring may be arranged in or on the drum or disc which carries the cam so that the ~ment device is provided with a spring D spring in resetting has to drive the spindle
- 15 back through the gear In either case any convenient form of fly governor dash-pot or other device acting as a speed regulator or brake may be used Or again, where average resetting is desired the relative posi-
- 20 tions of the driving and driven members, in the engaged and disengaged positions, taken in conjunction with the displacement of the cam or cams from the zero position, can be taken advantage of to introduce a reverse
- 25 drive, operated by the driving motor until the zero position is reached, and in this manner any desired ratio between backward and forward drive can be obtained
- It will be appreciated that in a multiple ³⁰ time-element device according to this invention a number of devices having very different time intervals may all be driven from the common driving member and that such time intervals as are decided on for each
- ²⁵ time element, may be made adjustable between zero and the limit decided on, and that quite apart from differences of construction in the time-element devices themselves, different time intervals may be
- 40 obtained by suitably arranging the gear ratios between the pinions on the common driving member and the cooperating gear wheels on the time-element devices
- In the accompanying drawings, which ⁴⁵ illustrate by way of example a multiple time-element device more especially intended for use in an automatic or semi-automatic electric power substation,
- Figure 1 is a diagrammatic view showing one construction of multiple time-element device according to this invention

Figure 2 is a plan of another construction showing the essential parts with more mechanical detail

Figure 3 is a transverse section on the line 3—3 of Figure 2, and Figures 4 and 5 are longitudinal sections 55

on the lines 4-4 and 5-5 respectively of Figure 2

60 With reference first to Figure 1, A indicates a motor driving through some known form of reduction gear not shown, a shaft B on which are mounted pinions B' B' B' and B⁴.

C' and two other similar devices C² and C² are disposed on the other side of the shaft These time-element devices each comprise a spindle carrying a gear wheel and some 70 means, not shown, of causing the spindle to move so as to bring its gear wheel into engagement with the cooperating pinion on the shaft B This movement of the spindle may be caused for instance by an electro- 75. magnet inside the casing shown as part of each time-element device. Each time-eleacting to return the spindle to its normal position when the electromagnet is deenergized and thus withdraw the gear wheel from engagement with the cooperating driving pinion

As shown in Figure 1 the time-element C is provided with a gear wheel E adapted to ⁸⁵ engage with the pinion B' and the time-elements C' C² C⁵ have gear wheels E' E² and E^a which cooperate with the driving pinions B^a B^a and B^a respectively

The time-element C has upon its spindle 90 a cam disc F which as it rotates moves a pivoted lever G controlling contacts .H Similarly the time-element C² has a cam disc F' acting through a pivoted lever G' on contacts H' These two time-elements C and C² are intended to reset themselves as soon as their gear wheels are disengaged from the driving pinions and therefore they are shown as provided with springs J and J' respectively which are wound up by the rotation of the spindles and cause those spindles to rotate rapidly in the opposite direction as soon as the gears are disengaged

The time-element devices C' and C' have not cams or like contact-operating devices 105 directly mounted on their spindles but drive contact-operating cams F^{*} and F^{*} through worm gears K' and K² These cams F² and F^s operate pivoted levers G^s and G^s which act to close the contacts H^s and H^s 110

The return or resetting movement of the time-element devices C' and C^a may be brought about by springs acting either directly on the spindles as in the case of the time-elements C and C² or, if the worm gear 115 is reversible, acting on the spindles carry-ing the cams F^2 and F^6 Further details are not given in connec-

tion with Figure 1 as that is intended to be a diagram showing merely the general ar- 120 rangement of the improved multiple timeelement device. Further details of some of the essential parts are shown in Figures 2, 8, 4 and 5. In the arrangement illustrated in Figures ¹²⁵

2, 8, 4 and 5 the driving motor is indicated at A' and the main driving shaft at A'. On this driving shaft are three pinions B¹, Ind B⁴. On one side of the main shaft B are two Figure 5 With the pinion B⁷ being shown on B^{4} .



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being imparted to its spindle by an arm L s or L' which forms part of the armature of

- an electromagnet L^s or L^s . The spindle armature arm L^r of an electromagnet L^s , carrying the gear wheel E^s forms part of the driving member being the pinion B^r one time-element device which may be em- (Figure 5) on the main shaft A^s In this ployed in connection with the synchroniz-
- 10 ing of the substation generator, and carries a contact-operating cam F⁴ This cam has an operating surface acting on levers G⁴ and G^s which act on two pairs of contacts H⁴ and H⁴
- Similarly the spindle carrying the gear wheel E^s drives a contact-operating cam F^s whose surfaces cooperate with pivoted levers G^{s} and G^{r} acting on contacts H^{s} and H^{t}
- The gear wheel E⁵, the cam F⁵ and one set 20 of levers and the contacts are shown more clearly in sectional elevation in Figure 4 and it will be understood that the construction of the cam F^{*} with its levers and contacts may be of a similar character
- As will be seen by reference to Figure 4 the spindle E^s upon which the gear wheel E' which forms part of a second timeelement device associated for example with an overload relay, is mounted can slide in the
- 30 cam F^{*} against the action of an adjustable spring D' The lever G^{*} does not act directly upon the contacts H^e but on another pivoted lever G^{s*} provided with a spring G^s 85 cam F⁵

The two other time-element devices, 1 e those shown on the right-hand side of Figure 2 are each driven through worm reduction The cam drum F^{*} of one of these zear 40 time-elements intended more especially for controlling the starting-up circuits for the substation generator, is driven by the worm M with which the spindle E' is in sliding engagement. Upon this spindle is mounted 45 the gear wheel E^{*} which can be brought into and out of operative engagement with the driving pinion B^e by means of the electromagnet L4 and its armature arm L5 A resetting spring J^a causes the return move-50 ment of the cam drum This cam drum F⁶ has three operating surfaces F', F' and F' (Figure 3) Each of these surfaces works in conjunction with a pivoted contact-operating lever One of these levers, that coop-55 erating with the surface F⁴, is shown at G³ matic or semiautomatic control of electric in Figure 3 with its contacts H⁸ The levers power substations and the multiple timeare held against the cam surfaces by springs of which one is shown at G¹⁰ (Figure 3) The cam ring or surface F⁹ is adjustable

60 relatively to the drum F⁶ to alter the posi-tion of its throw This adjustment may be effected by means of the nuts F¹⁰ shown in

Figure 2 The cam drum F^{11} of the remaining time-

brought into engagement either the gear conjunction with an underload relay to conwheel E⁴ or the gear wheel E⁵, the neces- trol the shutting-down circuits for the sub-sary motion of the particular gear wheel station generator, is likewise driven station generator, is likewise driven through a worm M', spindle E⁹ and gear wheel E^{10} the spindle being moved by the 70 time-element device however mechanism is provided for reversing the direction of ro- 75 tation of the cam drum F¹¹. This mechanism is shown in Figure 5 and comprises two pinions B^a and B^a mounted on a pivoted lever B¹⁰, and driven from the pinion B⁷ The spindle E⁹ can be moved so that the **80** gear wheel E¹⁰ either engages with the pinion B^o as shown or engages directly with the pinion B' The backward drive through the pinions B⁸ and B⁹ is stopped as soon as the cam drum returns to its zero position 85 for in that position a pin B¹¹ at the free end of the spring-controlled lever B¹⁰ (Figure 5) drops into a recess F^{19} in the upper edge of the cam ring F^{12} Thus the lever will rock slightly and take the pinion B^e 90 out of engagement with the pinion B⁷ The cam drum F¹¹ has three operating

rings or surfaces F¹², previously mentioned, and F¹³ and F¹⁴ The ring F¹³ is shown in Figure 8 in conjunction with a pivoted 95 lever G¹¹ and contacts H⁹ operated thereby A spring G^{12} keeps the lever G^{11} against its cam surface F^{12} Other levers and contacts The resetting spring J² is housed within the of similar construction are provided working in conjunction with the cam surfaces or 100 rings F13 and F14 but they are omitted for the sake of clearness

The cam ring or surface F14 is driven frictionally from the drum F¹¹ through a spring indicated at F¹⁵ (Figure 3) and has a pro- 105 jection F16 working between two fixed stops F¹⁷ and F¹⁸ (Figure 2) By this arrangement it is possible to ensure that the contacts H¹⁰ (Figure 2) controlled by this cam surface shall be operated directly at the first 110 part of either the forward or backward movement of the cam drum F^{11}

It will be appreciated that a multiple time-element device of the kind described can be used in many circumstances where 115 it is necessary to have a number of electrically-controlled operations performed in a proper sequence Operations of this nature are required for instance in the automatic or semiautomatic control of electric 120 element device particularly described is primarily intended for this purpose

What I claim as my invention and desire 126 to secure by Letters Patent 15 .-

1 In a multiple electric time-element device, the combination of a single driving member, means for rotating this member at The cam drum F¹¹ of the remaining time- a slow and uniform speed, a plurality of 65 element device which may be employed in separate and dissimilar time-element con-

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ticular time characteristics of the device, and a plurality of separate and independently s actuated mechanisms respectively adapted

- to bring the driving connections into or out of operative engagement, with the single driving member
- 2 In a multiple electric time-element de-10 vice, the combination of a single driving shaft, means for rotating the shaft at a slow and uniform speed, a plurality of pinions mounted on the shaft, and a plurality of separate and dissimilar time-clement contact-
- 15 operating devices each comprising a plurality of contacts, a rotatable contact-maker for actuating such contacts, a gear wheel, an operative connection between the gear wheel and the contact maker suited to the particu-
- 20 lar time characteristics of the device, and an electromagnetic mechanism for bringing the gear wheel into operative engagement with the appropriate pinion on the driving shaft 3 In a multiple electric time-element de-
- so vice, the combination of a single driving shaft, an electric motor for rotating the shaft at a slow and uniform speed, a pluiality of pinions mounted on the shaft, and a plurality of separate time-element contact-oper-
- 30 ating devices each comprising a rotatable contact-maker, an axially movable spindle, a gear wheel mounted on the spindle, an operative connection between the spindle and the contact-maker suited to the particular time
- ^{/85} characteristics of the device, an electromagnetic mechanism for moving the spindle axially so as to bring the gear wheel into operative engagement with the appropriate pinion on the driving shaft, and means for
- 40 returning the spindle and the contact-maker to their initial positions when the device is disengaged from the driving shaft the said means in at least one of the devices including a spring whereby the contact-maker is in-45 stantaneously reset.

4. In a multiple electric time-element device, the combination of a single driving shaft, means for rotating the shaft at a slow and uniform speed, a plurality of pinions 50 mounted on the shaft, and a plurality of separate and dissimilar time-element contactoperating devices each comprising a pluial-

- ity of contacts, a rotatable disc, a plurality of cam rings so disposed on the disc that they 88 will operate the contacts when the disc is rotated, a gear wheel, an operative connec-
- tion between the gear wheel and the disc suited to the particular time characteristics of the device, and an electromagnetic mecha-⁶⁰ nism for bringing the gear wheel into oper-
- ative engagement with the appropriate pinion on the driving shaft. 5. In a multiple electric time-element de-

vice, the combination of a single driving shaft, means for rotating the shaft at a slow

tact-operating devices, an operative driving and uniform speed, a plurality of pinions connection for each device suited to the par- mounted on the shaft, and a plurality of separate and dissimilar time-element contact-operating devices each comprising a rotatable contact-maker, a spindle, a gear 70 wheel mounted on the spindle, an operative during connection between the spindle and the contact-maker, and means for moving the spindle so as to bring the gear wheel into or out of operative engagement with the ap- 75 propriate pinion on the driving shaft, the operative driving connection in at least one of the devices being such that the spindle drives the contact-maker directly but can slide axially relative thereto

6 In a multiple electric time-element device, the combination of a single driving shaft, means for rotating the shaft at a slow and uniform speed, a plurality of pinions mounted on the shaft, and a plurality 85 of separate and dissimilar time-element contact-operating devices each comprising a rotatable contact-maker, an axially movable spindle, a gear wheel mounted on the spindle, an operative driving connection between the spindle and the contact-maker suited to the particular time characteristics of the device, and means for moving the spindle axially so as to bring the gear wheel into or out of operative engagement with the appropriate pinion on the driving shaft, the operative driving connection in at least one of the devices comprising a sleeve so mounted on the spindle as to rotate therewith but to remain unaffected by the axial movement 100 thereof, a worm on the sleeve, and a worm wheel engaging with the worm and connected directly to the contact-maker

7. In a multiple electric time-element device, the combination of a single driving 105 member, means for rotating this member at a slow and uniform speed, a plurality of separate and dissimilar time-element contact-operating devices, an operative driving connection for each device suited to the par- 110 ticular characteristics of the device, and a plurality of separate and independently actuated mechanisms respectively adapted to bring the driving connections into or out of operative engagement with the single 115 driving member, the operative driving connection for at least one of the devices including worm gearing and reversing gear-

8. In a multiple electric time-element de- 120 vice, the combination of a single driving member, means for rotating this member at a slow and uniform speed, a plurality of separate and dissimilar time-element contact-operating devices, an operative driving 125 connection for each device suited to the particular characteristics of the device, and a plurality of separate and independently actuated mechanisms respectively adapted to bring the driving connections into or out of 130

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ing member, at least one of the contact-operating devices comprising a rotatable contact-maker, a spindle, a gear wheel mounted

- 5 on the spindle, worm gearing between the spindle and the contact-maker, two pinions driven in opposite directions by the driving member, and electromagnetic mechanism for bringing the gear wheel into operative en-
- 10 gagement with one or other of the two pinions whereby the contact-maker can be driven either in the forward or the reverse direction
- 9 In a multiple electric time-element de-15 vice, the combination of a single driving member, means for rotating this member at a slow and uniform speed, a plurality of separate and dissimilar time-element contact-operating devices, an operative driving
- 20 connection for each device suited to the particular time characteristics of the device, and a plurality of separate and independently actuated mechanisms respectively adapted to bring the driving connections into or out of
- 25 operative engagement with the single driving member, at least one of the contactoperating devices including a plurality of contacts, a rotatable disc, a plurality of cam rings so disposed on the disc that they will
- 30 operate the contacts when the disc is rotated whereby the device can be employed to cause a series of operations to be per--formed in a predetermined sequence, and means for adjusting at least one of the cam
- 35 rings relatively to the disc whereby the time interval between successive stages in the sequence of operations may be varied

10 In a multiple electric time-element device, the combination of a single driving 40 member, means for rotating this member at a slow and uniform speed, a plurality of separate and dissimilar time-element contact-opérating devices, an operative driving connection for each device suited to the par-45 ticular characteristics of the device, and a plurality of separate and independently actuated mechanisms respectively adapted to

- bring the driving connections into or out of operative engagement with the single driv-50 ing member, at least one of the contact-operating devices including a rotatable disc, a plurality of cam rings on the disc one of these rings being driven frictionally from
- the disc, a finger or projection on the fric-55 tionally driven cam ring, two fixed stops to limit the movement of the finger or projection and a plurality of contacts operated by the cam rings.

11 In a multiple electric time-element device, the combination of a single driving shaft, means for rotating this shaft at a slow and uniform speed, a plurality of pin-ions mounted on the shaft, and a plurality of separate and dissimilar time-element con-

operative engagement with the single driv- tatable contact-maker, a gear wheel, an operative driving connection between the gear wheel and the contact-maker suited to the particular time characteristics of the device. and means for moving the gear wheel into ⁷⁰ or out of engagement with the appropriate pinion on the driving shaft, at least one of the devices including a spring whereby the contact-maker 18 instantaneously reset when the gear wheel is disengaged from the pin- 75 ion, and worm gearing which forms part of the operative driving connection and is so arranged as to allow the contact-maker to be reset by the spring

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12 In a multiple electric time-element ⁸⁰ device, the combination of a single driving shaft, means for rotating this shaft at a slow and uniform speed, a plurality of pinions mounted on the shaft, and a plurality of separate and dissimilar time-element con- 85 tact-operating devices each comprising a rotatable contact-maker, a gear wheel, an operative driving connection between the gear wheel and the contact-maker suited to the particular time characteristics of the 90 device. and means for moving the gear wheel into or out of engagement with the appropriate pinion on the driving shaft, at least one of the devices having means for instantaneously resetting the contact-maker when the gear wheel is disengaged from the pinion, while another of the devices has means whereby the driving shaft drives the contact-maker in the reverse direction for 100 resetting purposes.

13 In a multiple electric time-element device, the combination of a single driving shaft, means for rotating this shaft at a slow and uniform speed, a plurality of pinions mounted on the shaft, and a plurality 105 of separate and dissimilar time-element contact-operating devices each comprising a rotatable contact-maker, a gear wheel, an operative driving connection between the ear wheel and the contact-maker suited to 110 the particular time characteristics of the device, and means for moving the gear wheel into or out of engagement with the appropriate pinion on the driving shaft, at least one of the devices including means whereby the driving shaft drives the contactmaker at a slow speed in the forward direction and resets it by driving it at a slow but different speed in the reverse direction

14 In a multiple electric time-element de- 120 vice, the combination of a single driving member, means for rotating this member at a slow and uniform speed, a plurality of separate and dissimilar time-element contact-making devices, an operative driving 125 connection for each device suited to the particular time characteristics of the device, and a plurality of separate and independently actuated controlling mechanisms retact-operating devices each comprising a ro- spectively adapted to bring the driving con- 130

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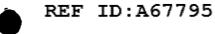
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nections into or out of operative engagement moved by the controlling mechanism into with the driving member, the operative driv- operative engagement with one or the other ing connection for at least one of the devices of the two pinions. including reversing gearing comprising two In testimony whereof I have signed my
pinions driven in opposite directions by the name to this specification driving member and a gear wheel which is FREDERICK NORMAN LINSTOW.

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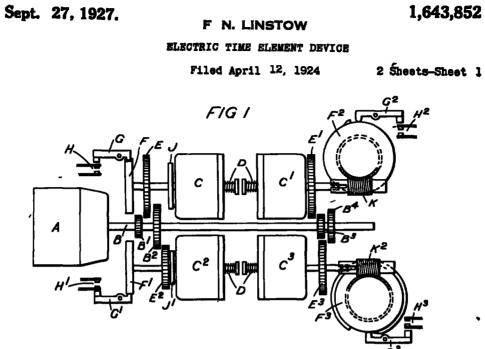
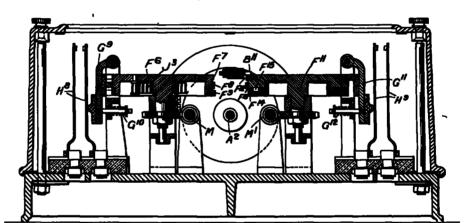
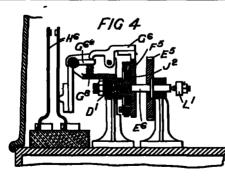
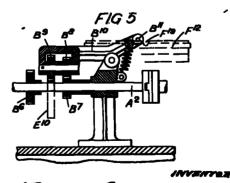


FIG 3



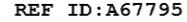




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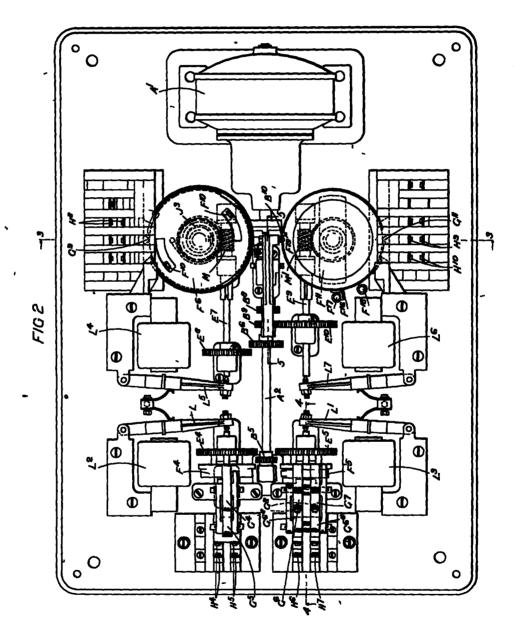
Sept. 27, 1927

F N. LINSTOW ELECTRIC TIME ELEMENT DEVICE

Filed April 12, 1924

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INVENTOR y F h Linetow, Matan, Cont. more & In

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